

The 19th North American Meeting of the Urban Economics Association  
@ Université du Québec à Montréal, Montréal, Canada

# Understanding Regional Dynamics

October 3, 2025

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## Broad motivation

- Quantitative spatial models typically rely on **equilibrium uniqueness** to conduct unambiguous counterfactual analyses
- By design, QSMs do “**not aim to provide a fundamental explanation for the agglomeration of economic activity**” (Redding & Rossi-Hansberg, 2017)
- Agglomeration in these models are due to differences in “**unobserved fundamentals**” or “**first nature**” of Krugman (1993)
- Under big shocks and/or alternative possibilities, **agglomeration forces** and **multiple equilibria** can be important (Bleakley & Lin, 2012; Lin & Rauch, 2022)
- How **models of spatial agglomeration** behaves in this case?  
What **spatial patterns** may be explained/represented by “**second nature**”?

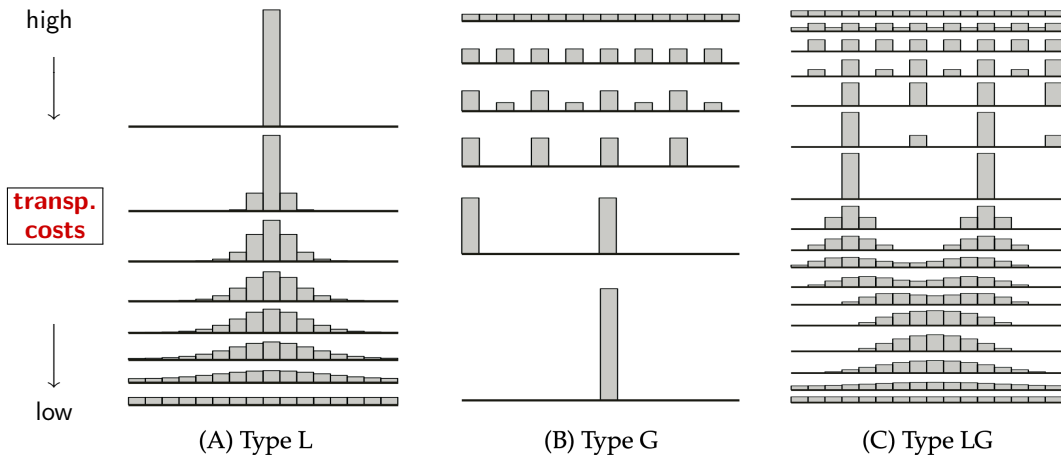
## Static regional models and their taxonomy (Akamatsu *et al.*, 2017)

- Two general types of dispersion forces
  - Crowding *within* each location : “**local**” dispersion forces  
e.g., inelastic supply of housing (nontraded good) (Helpman, 1998)
  - Crowding *across* locations : “**global**” dispersion forces  
e.g., immobile factor + trade (Krugman, 1991)
- Implied model types:

	Local	Global	Notable instances
1. Type L	✓		Helpman (1998); Redding & Sturm (2008); Allen & Arkolakis (2014)
2. Type G		✓	Krugman (1991); Puga (1999); Forslid & Ottaviano (2003)
3. Type LG	✓	✓	Tabuchi (1998); Pflüger & Tabuchi (2010); Kucheryavyy <i>et al.</i> (2024)

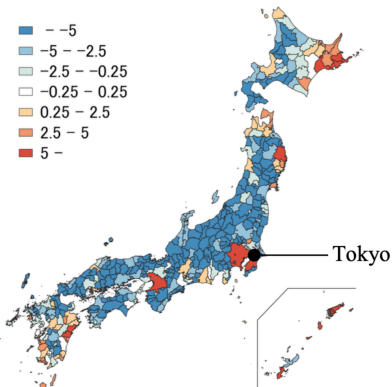
- Notably, the great majority of conventional QSMs are **Type L** (Redding, 2025)

# Static models: Different type, different spatial implications

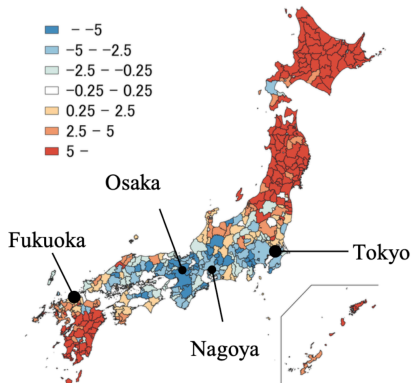


# Static models: Different type, different spatial implications

- Spatial implications are in the *opposite* directions (Sugimoto *et al.*, 2025)



(B) Removal of highways (Type L)



(C) Removal of highways (Type LG)

## This study

- Extend this research program to an explicitly dynamic setting.
  - As a specific example, we examine **Allen & Donaldson (2020) [AD]**  
“Persistence and Path Dependence in the Spatial Economy” NBER w28059
    - A good starting point: Clean, tractable, & various microfoundations
    - Can be seen as a dynamic version of Allen & Arkolakis (2014)  
⇒ Should resemble “Type L” static models . . . We will confirm this.
  - Approach: Agglomeration as instability of symmetry (Papageorgiou & Smith, 1983)
    - e.g., New Economic Geography
- Q1. How *endogenous forces* drive agglomeration?
- Q2. What *spatial patterns* can emerge?

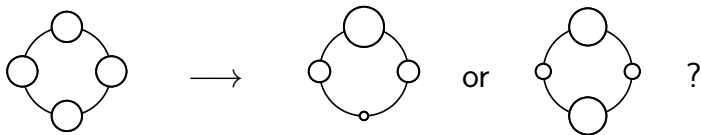
# The (symmetric) AD framework

We shall stick to the most symmetric version.

- $N$  locations with homogeneous characteristics
- Iceberg trade frictions btw. locations  $\{\tau_{ij}\}$ ,  $\tau_{ij} \geq 1$
- Iceberg migration frictions btw. locations  $\{\mu_{ij}\}$ ,  $\mu_{ij} \geq 1$
- Population distribution  $\mathbf{L}_t = (L_{i,t})_{i=1}^N$  at time  $t \in \{0, 1, 2, \dots\}$
- Perfectly competitive Armington with *local* but intertemporal externalities.
  - Amenity at time  $t$ :  $u_i(\mathbf{L}) = L_{i,t}^{\beta_1} \cdot L_{i,t-1}^{\beta_2}$  ( $\beta_1 < 0$ ,  $\beta_2 > 0$ )
  - Productivity at time  $t$ :  $a_i(\mathbf{L}) = L_{i,t}^{\alpha_1} \cdot L_{i,t-1}^{\alpha_2}$  ( $\alpha_1 > 0$ ,  $\alpha_2 > 0$ )
- Market/migration eqm. defines discrete-time dynamics:  $\mathbf{L}_t = \mathbf{F}(\mathbf{L}_{t-1})$ .

## Symmetric four-location economy: A minimal testbed

- By assuming a symmetric geographical setting, we can focus on the *symmetric steady-state equilibrium*  $\bar{\mathbf{L}} = (\frac{1}{N}, \frac{1}{N}, \frac{1}{N}, \dots, \frac{1}{N})$  because  $\bar{\mathbf{L}} = \mathbf{F}(\bar{\mathbf{L}})$ .
- Instability of  $\bar{\mathbf{L}} \Rightarrow$  Some form of “endogenous” agglomeration.
- The four-location circular economy makes analysis simple yet relevant:



- In fact,
  - Type L static models: Only a single-peaked agglomeration.
  - Type G static models: Poly-centric agglomeration (multiple cities).

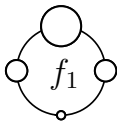


## Stability of symmetric steady state

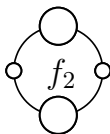
- Friction matrices have special structures:

$$\begin{bmatrix} 1 & \phi & \phi^2 & \phi \\ \phi & 1 & \phi & \phi^2 \\ \phi^2 & \phi & 1 & \phi \\ \phi & \phi^2 & \phi & 1 \end{bmatrix} \quad \phi = \begin{cases} r \in (0, 1) & \text{(freeness of trade)} \\ s \in (0, 1) & \text{(freeness of migration)} \end{cases}$$

- This allows for the analytical characterization of stability of  $\bar{L}$ .
- If the absolute value of the “**net agglomeration forces**”  $f_1$  and  $f_2$  ( $\approx$  **agglom. force**  $\div$  **disp. force**) are smaller than 1,  $\bar{L}$  is stable.



Mono-centric



Poly-centric

# Net agglomeration forces in the AD framework

Concretely, for  $k = 1, 2$ ,

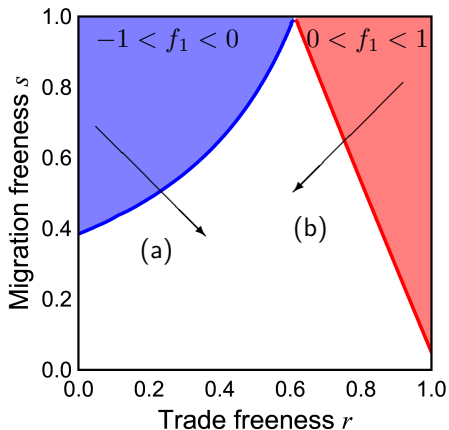
$$f_k = \frac{f_k^\sharp}{f_k^\flat} \quad \text{where} \quad \begin{cases} f_k^\sharp = \alpha_2 A_k + \beta_2 + \lambda_k \theta^{-1} (1 - \lambda_k^2)^{-1}, \\ f_k^\flat = -\alpha_1 A_k - \beta_1 + B_k + \theta^{-1} (1 - \lambda_k^2)^{-1}, \end{cases}$$

$$A_k = \frac{\chi_k + (\sigma - 1)(1 + \chi_k)}{1 + (\sigma - 1)(1 + \chi_k)} \in (0, 1), \quad B_k = \frac{1 - \chi_k}{1 + (\sigma - 1)(1 + \chi_k)} > 0.$$

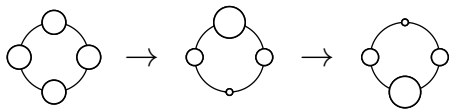
- $\sigma$ : Armington CES elasticity.
- $\theta$ : Migration friction (Fréchet dispersion parameter)
- $\chi_k \in (0, 1)$ : a trade cost index,  $\lambda_k \in (0, 1)$ : a migration cost index.

# Agglomeration as instability of symmetry (1/3)

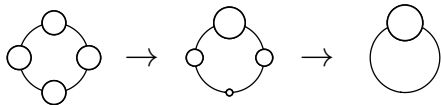
Stability region for the monocentric direction ( $|f_1| < 1$ )



(a) Agglomeration with oscillation.



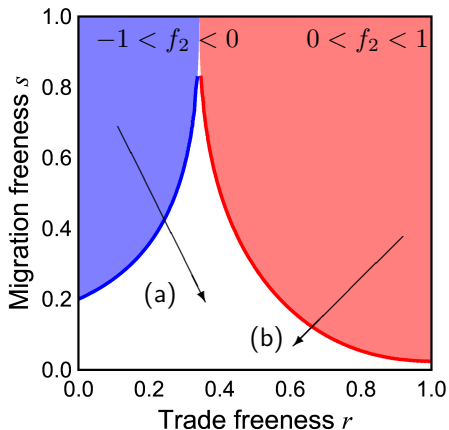
(b) Agglomeration without oscillation.



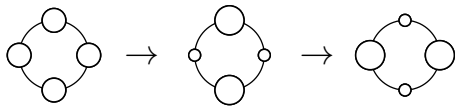
$$(\sigma, \theta, \alpha_1, \beta_1, \alpha_2, \beta_2) = (8, 6, 0.7, -0.4, 0, 0).$$

## Agglomeration as instability of symmetry (2/3)

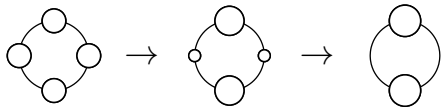
Stability region for the polycentric direction ( $|f_2| < 1$ )



(a) Agglomeration with oscillation.



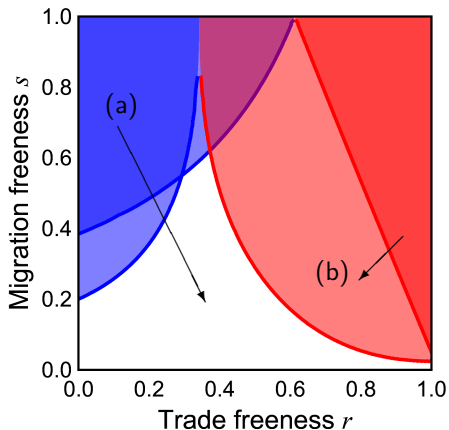
(b) Agglomeration without oscillation.



$$(\sigma, \theta, \alpha_1, \beta_1, \alpha_2, \beta_2) = (8, 6, 0.7, -0.4, 0, 0).$$

## Agglomeration as instability of symmetry (3/3)

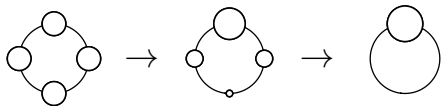
The stability region of symmetry  $\bar{L}$ :  $|f_1| < 1$  *and*  $|f_2| < 1$



(a) Agglomeration with oscillation.

- Both mono-centric & poly-centric spatial patterns

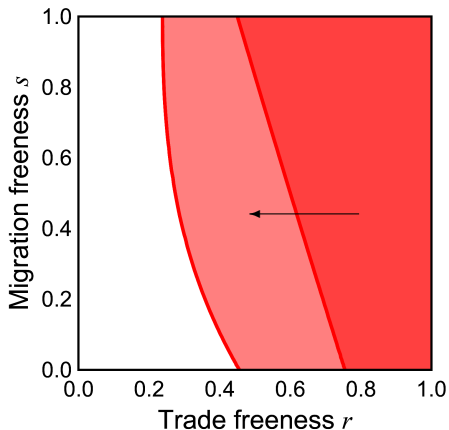
(b) Agglomeration without oscillation.



- Only mono-centric spatial patterns

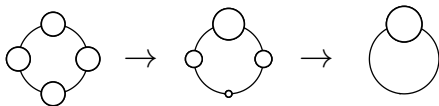
$$(\sigma, \theta, \alpha_1, \beta_1, \alpha_2, \beta_2) = (8, 6, 0.7, -0.4, \mathbf{0}, \mathbf{0}).$$

## A more relevant case: Estimates for the US from AD



$$(\sigma, \theta, \alpha_1, \beta_1, \alpha_2, \beta_2) = (5, 6, 0.3, -0.4, 0.1, 0.3)$$

- Agglomeration without oscillation.



- Only monocentric spatial patterns.
- Similar to the Allen–Arkolakis model in the static world.

## Summary

- “Endogenous” spatial patterns in the Allen–Donaldson framework
  - As expected, behavior similar to the Allen–Arkolakis model ( $\approx$  “Type L”)
- 
- Simple geographical settings are still important in understanding the basic mechanics of spatial models with both agglomeration and dispersion forces.
  - In doing so, having four locations is crucial for studying spatial patterns.
  - What can be said for the empty cells? Also, quantitative relevance?

	Type L	Type G	Type LG
Static	Helpman (1998), Allen & Arkolakis (2014)	Krugman (1991), Puga (1999) (§3)	Tabuchi (1998), Kucheryavyy <i>et al.</i> (2024)
Dynamic	Allen & Donaldson (2020)	???	???

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